CTL-property transformations along an incremental design process

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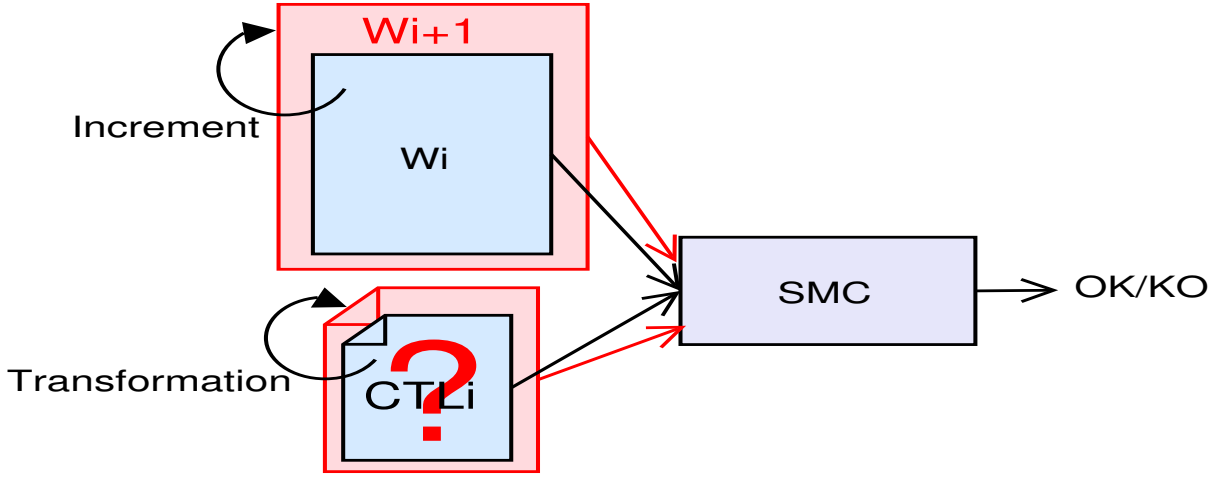
Context

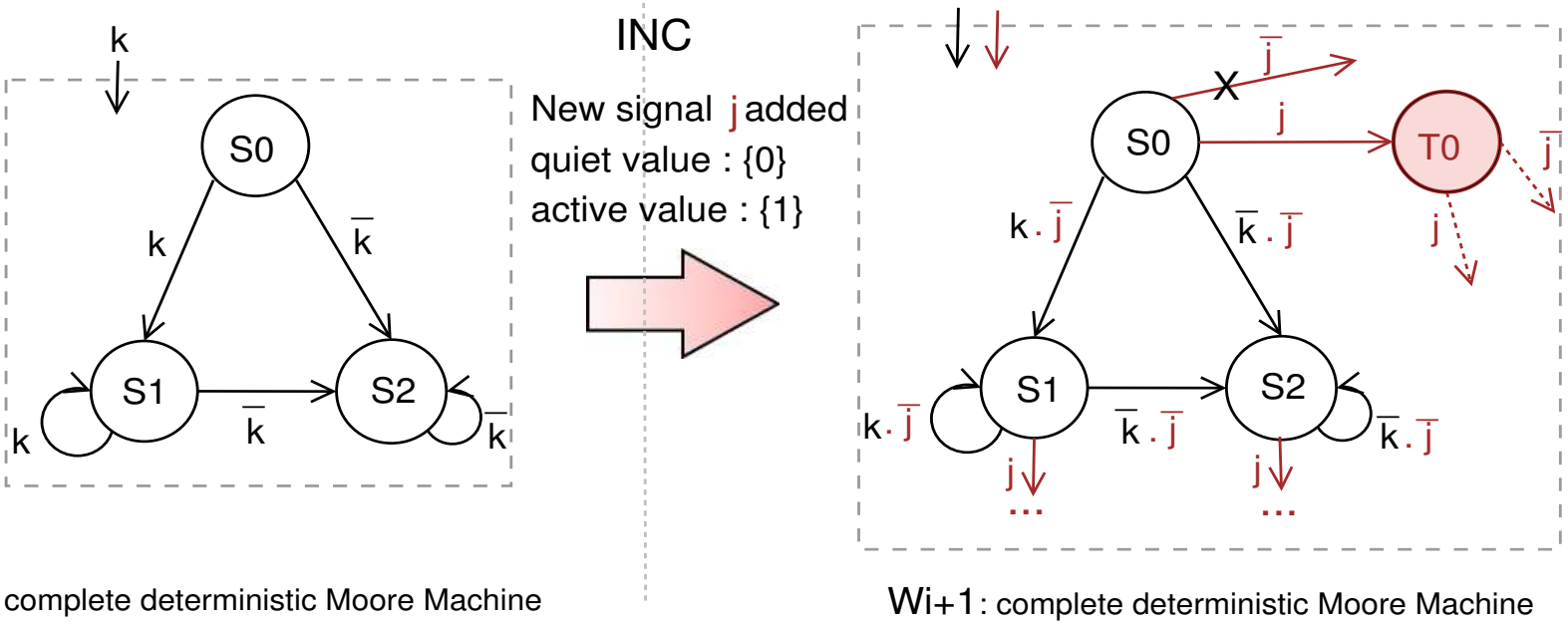
- Incremental strategy : **successive additions of new behaviours**
  - Observation of hardware designers (pipeline flow)
  - Specification by CTL formulae and symbolic model checking



- ACTL Property preservation $W_{i+1} \longrightarrow W_i$ (Grumberg and Long 1991)
- ECTL Property preservation $W_i \longrightarrow W_{i+1}$ (Loiseaux and Graf 1995)
- Complementary to Refinement strategy (B-Method Abrial)
- Differs to Feature integration (M. C. Plath and M. D. Ryan, D. Méry and D. Cansell)

Increment Definition

- Increment INC is a set of new events
  - Each event has quiet values and active values (val_qt,val_act)
  - No new initial state
  - No behaviour overriding



Wi : complete deterministic Moore Machine

Wi+1 : complete deterministic Moore Machine

- W_{i+1} simulates W_i
- $K(W_{i+1})$ simulates $K(W_i)$ (Kripke structure)
- $K(W_{i+1})$ includes $K(W_i)$ with the state that were in $K(W_i)$ tagged with the quiet value

CTL-property transformations

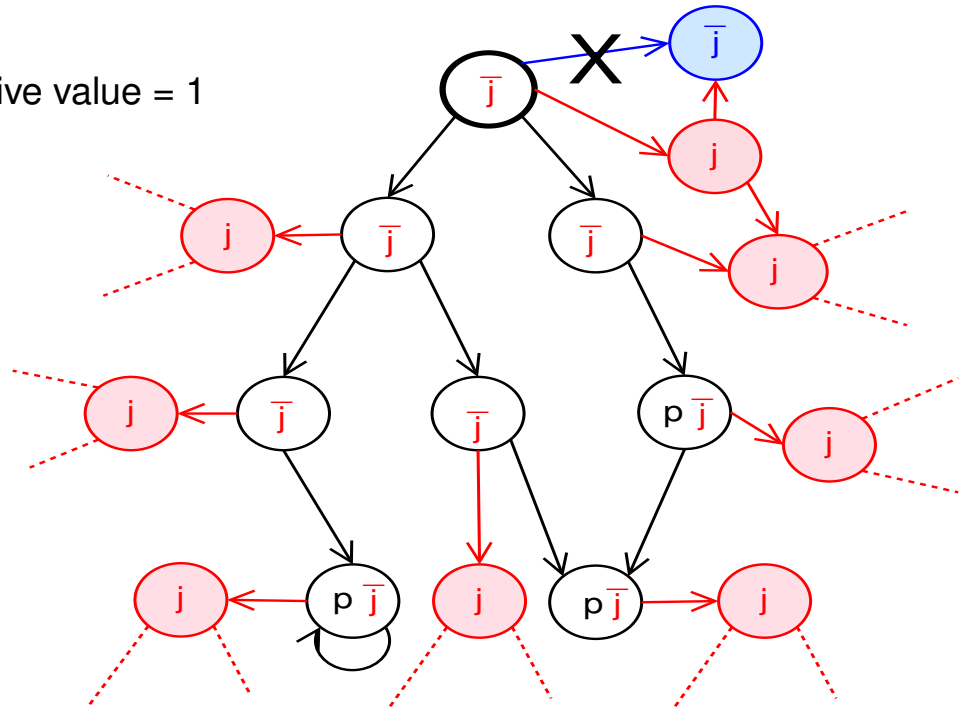
- Goal : Let be φ such that $W_i,s_0 \models \varphi$, what is φ' such that :
  K(W_i),$s_0 \models \varphi \Leftrightarrow K(W_{i+1}),s_0$' $\models \varphi$' with $K(W_{i+1})$ obtained by increment from $K(W_i)$
- Principle : Reduction of the computational tree explored

Example : transformation of AFp

$K(W_i) \models$ AFp

INC : j,quiet value = 0,active value = 1

$K(W_{i+1}) \models$ AF(p or j)



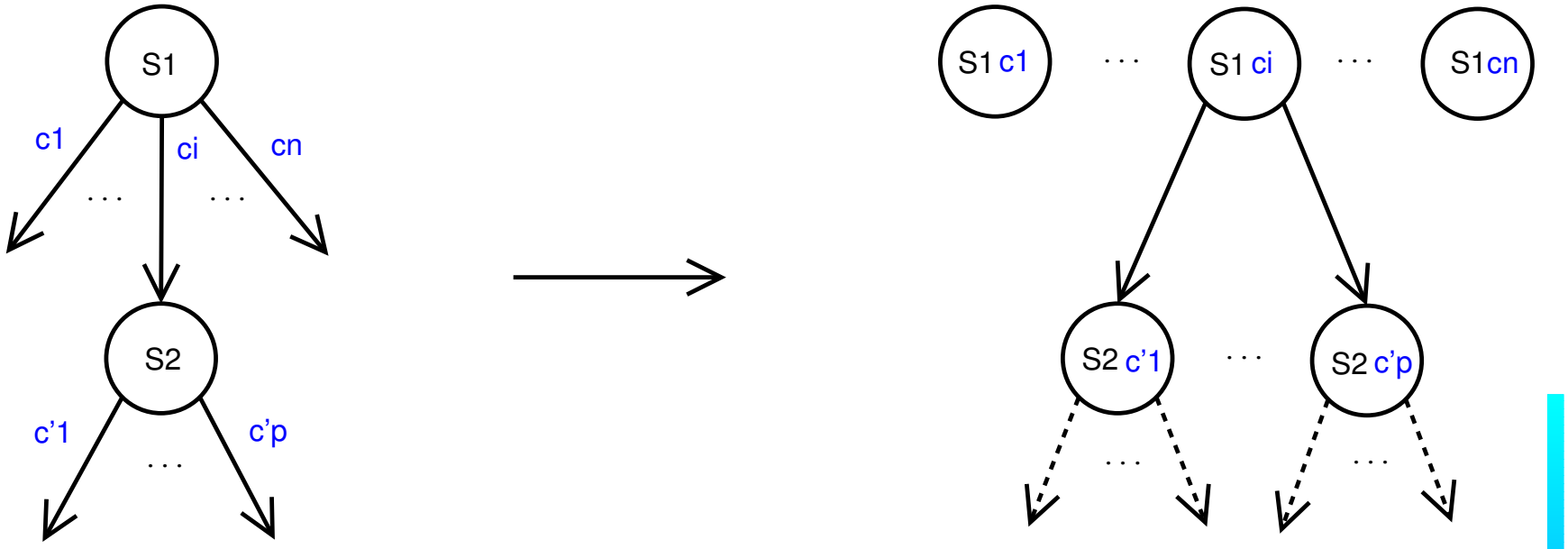
Results and Concluding remarks

- Transformation rules
  - All CTL operators are transformable (bi-implication)
  - All CTL formulae are transformable by recursively applying the transformation
  - The transformed CTL formulae have the same complexity as the initial ones
- Application to a concrete component design (VCI-PI protocol converter)
  - System with 330-450 boolean variables
  - Transformations applying on 80 properties automatically
  - The transformed properties do not increase significally the time of verification
- Further studies :
  - Taking advantage of the increment graph structure
  - The opposite analysis
  - Assume-Guarantee verification process

Transformations rules

Φ = p	$\Leftrightarrow$	Φ' = p
Φ = not f	$\Leftrightarrow$	Φ' = not f'
Φ = EXf	$\Leftrightarrow$	Φ' = (e = val_qt) $\Rightarrow$ EXf'
Φ = EFf	$\Leftrightarrow$	Φ' = E((e = val_qt) U f')
Φ = EGf	$\Leftrightarrow$	Φ' = EG((e = val_qt) and f')
Φ = Ef U g	$\Leftrightarrow$	Φ' = E(((e = val_qt) and f') U g')
Φ = AXf	$\Leftrightarrow$	Φ' = (e = val_qt) $\Rightarrow$ AXf'
Φ = AFf	$\Leftrightarrow$	Φ' = AF((e $\neq$ val_qt) or f')
Φ = Af U g	$\Leftrightarrow$	Φ' = A(((e = val_qt) and f') U ((e $\neq$val_qt) or g'))
Φ = AGf	$\Leftrightarrow$	Φ' = A(((e = val_qt) and f') W (e $\neq$ val_qt))
Φ = Af W g	$\Leftrightarrow$	Φ' = A(f' W (g' or (e $\neq$ val_qt)))

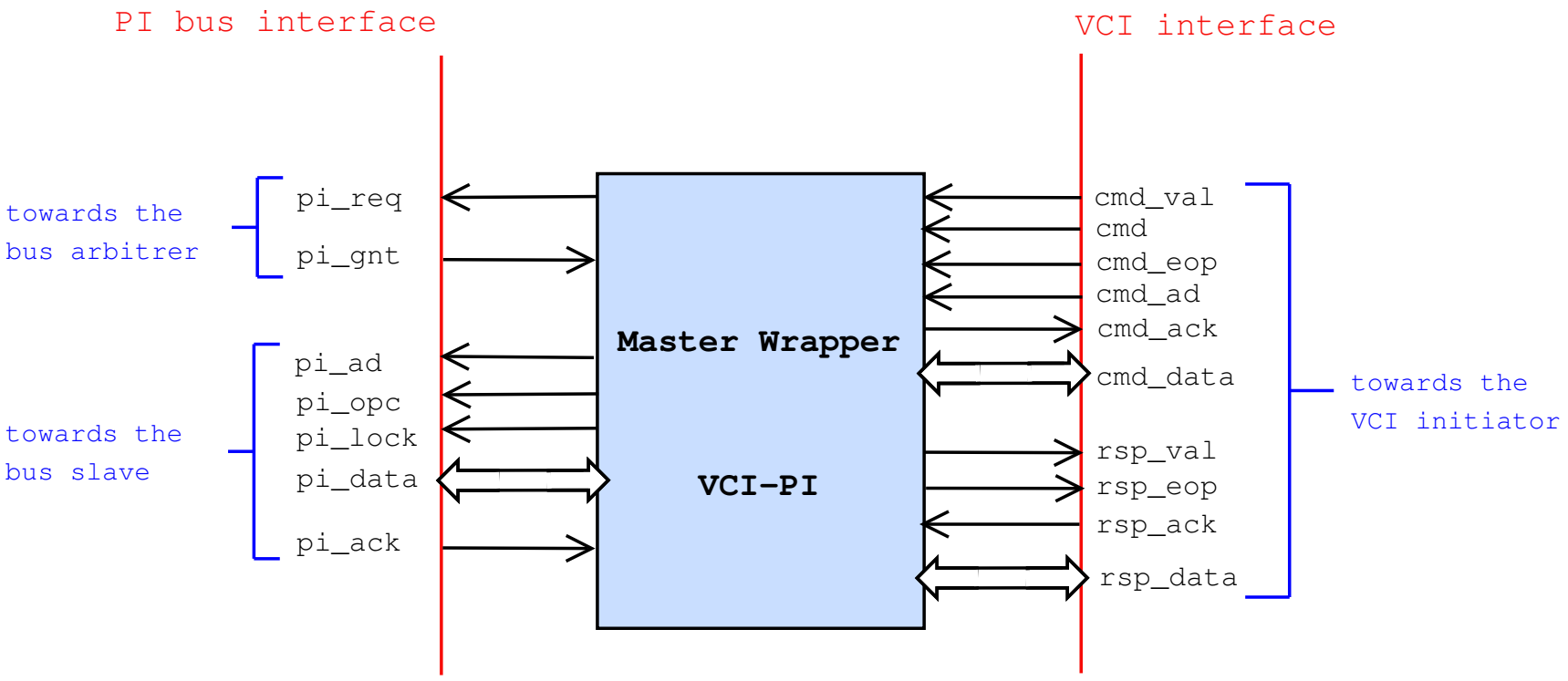
Transformation of a Moore machine into a Kripke structure



Moore Machine

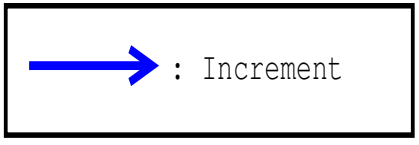
Kripke Structure

VCI-PI Wrapper interface

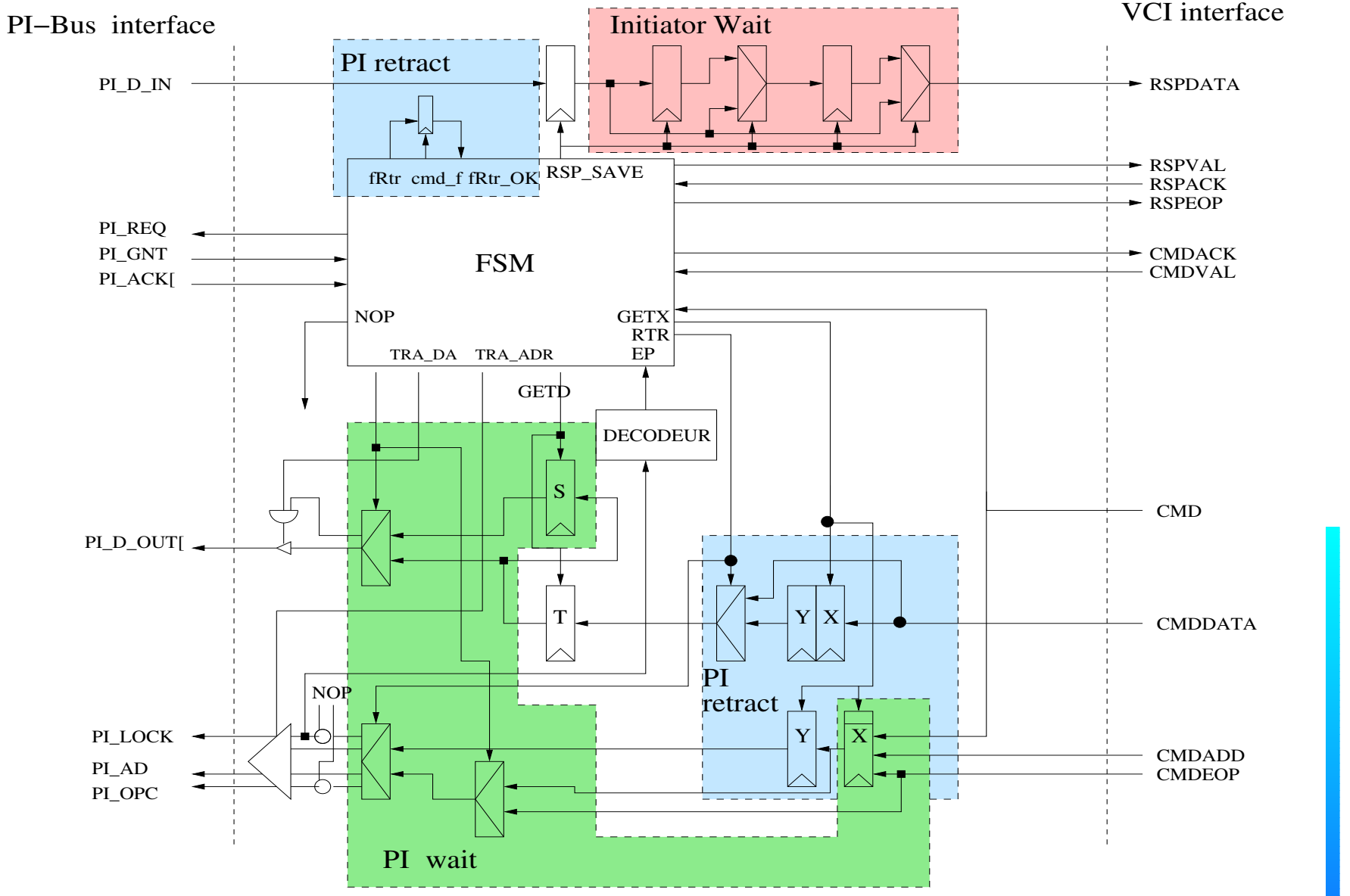


Wrappers Hierarchy

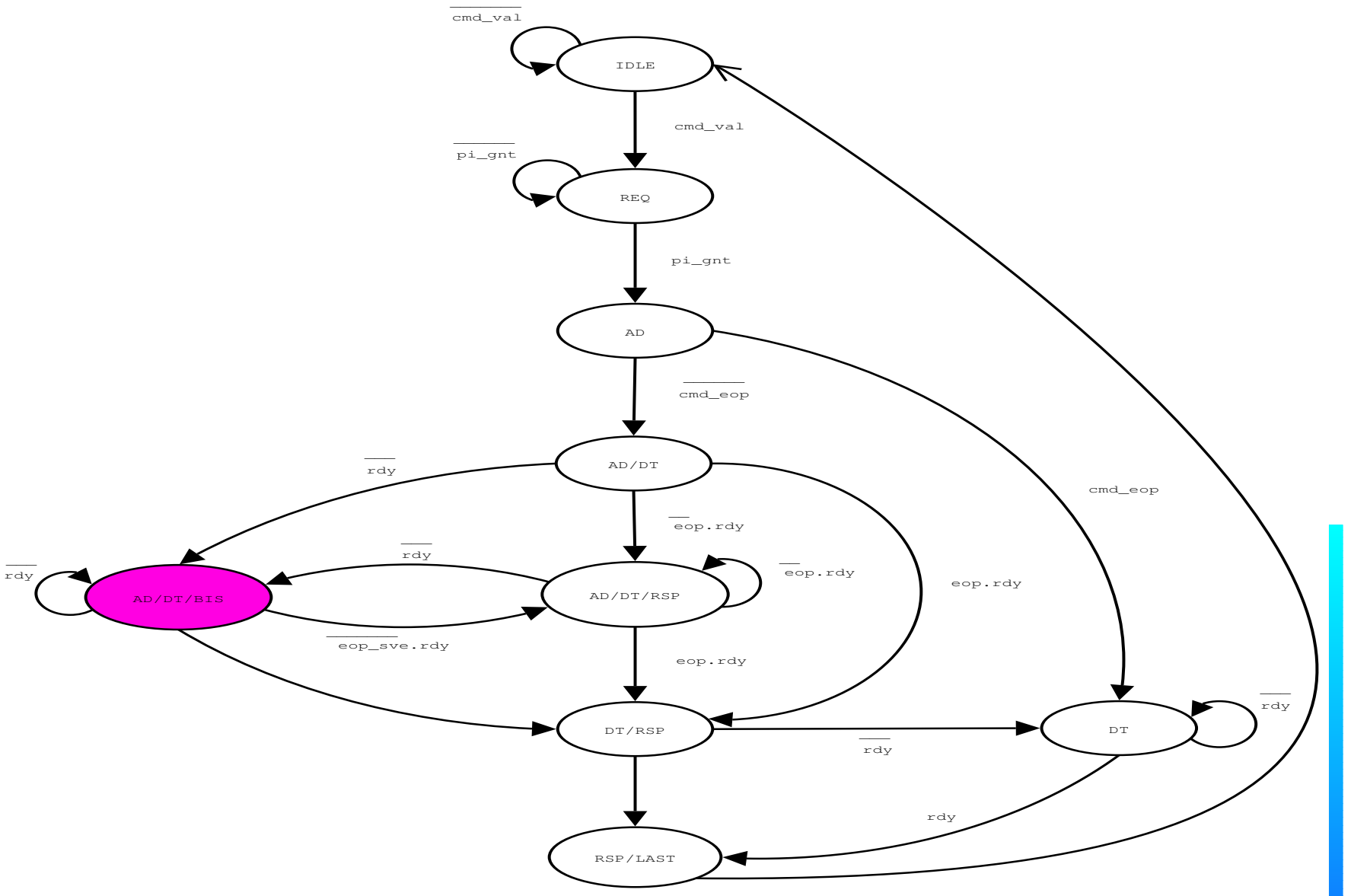
Type of event considered	Initiator is always ready	Initiator may impose wait states
Target is always ready pi_rsp = RDY	A cmd_ack = 1 ; cmd_val = 1 rsp_val = 1 ; rsp_ack = 1	A′ cmd_ack = 1 ; cmd_val = {0,1} rsp_val = 1 ; rsp_ack = {0,1}
Target may impose wait states pi_rsp = {RDY,WAIT}	B cmd_ack = {0,1} ; cmd_val = 1 rsp_val = {0,1} ; rsp_ack = 1	B′ cmd_ack = {0,1} ; cmd_val = {0,1} rsp_val = {0,1} ; rsp_ack = {0,1}
Target may impose retract pi_rsp = {RDY,WAIT,RTR}	C cmd_ack = {0,1} ; cmd_val = 1 rsp_val = {0,1} ; rsp_ack = 1	C′ cmd_ack = {0,1} ; cmd_val = {0,1} rsp_val = {0,1} ; rsp_ack = {0,1}



VCI-PI Wrappers Datapath (C)



VCI-PI Wrappers FSM (B')



VCI-PI Wrappers FSM(A and B)